Finding Mixed-Memberships in Social Networks

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Abstract

This paper addresses the problem of unsupervised group discovery in social networks. We adopt a nonparametric Bayesian framework that extends previous models to networks where the interacting objects can simultaneously belong to several groups (i.e., *mixed membership*). For this purpose, a hierarchical nonparametric prior is utilized and inference is performed using Gibbs sampling. The resulting mixed-membership model combines the usual advantages of nonparametric models, such as inference of the total number of groups from the data, and provides a more flexible modeling environment by quantifying the degrees of membership to the various groups. Such models are useful for social information processing because they can capture a user's multiple interests and hobbies.

Introduction

Given a social network, a common task is to discover group structure within the network. Generally speaking, the approaches to group discovery (a.k.a., community finding) break down along three classes: graph-theoretic (Newman 2004; Palla, Barabasi, & Vicsek 2007), compression-based (Chakrabarti & Faloutsos 2006), and probabilistic (Kemp *et al.* 2006; Airoldi *et al.* 2006). In this paper, we present a probabilistic approach that (1) is nonparametric and (2) accounts for different mixtures of group memberships for each object, over all possible groups that are present in the whole network. These two characteristics make our model an excellent fit for social information processing.

A fundamental issue in all group discovery problems is that the actual number of groups is unknown *a priori*. In most cases, this is addressed by running the same model several times with a different cardinality each time and selecting the one that provides the best fit to the data (e.g., based on a Bayes factor criterion in the case of Bayesian techniques). Obviously, it would be preferable to develop techniques that can infer the number of groups from the data and simultaneously examine hypotheses of different cardinalities. So, we adopt a nonparametric Bayesian framework, where the size

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of the model (i.e., the number of groups) can adapt to the available data and readily accommodate outliers.

In this respect, our formulation is similar to the Infinite Relational Model (IRM) (Kemp *et al.* 2006). However, our *infinite mixed membership model* (IMMM) is able to capture the possibility that objects belong to several groups and quantify their relative degrees of membership. For this purpose, it is perhaps more natural to talk with respect to identities rather than groups. In particular, we assume that each object has an unknown identity which can consist of one or more components. We attempt to discover those components and estimate their proportions. Our proposed framework combines all the advantages of standard Bayesian techniques such as integration of prior knowledge in a principled manner, seamless accommodation of missing data, quantification of confidence in the output, etc.

The rest of the paper is organized as follows. Section 2 reviews IRM, which serves as the basis for further developments. Sections 3 and 4 describe IMMM and several experimental studies, respectively. We conclude the paper in Section 5. It should also be noted that even though the majority of this paper's presentation is restricted to objects of a single type or domain (e.g., *people*) and pairwise binary links/connections of a single type (e.g., *is friend of*), the proposed framework can be readily extended to links of various types between several domains. Furthermore, our mixed-membership model can also be used to predict unobserved/missing links among objects. For brevity, we have omitted a discussion of this application.

Preliminaries

Consider a social network which contains observations about links between objects of various types (e.g., people, organizations, movies, etc). These links can be of various types and take binary, categorical, or real values. Without loss of generality, we will restrict the presentation to pairwise binary links $R_{i,j}$ in a single domain (i.e. *person i is friend of person j*) and follow the formalism introduced in IRM (Kemp *et al.* 2006). We present examples with two domains in subsequent sections. The basic goal is to group the objects based on the observables, i.e., the links. A generative model can be defined which postulates that the likelihood of any link between a pair of objects i and j depends exclusively on their respective identities I_i and I_j. In this respect, IRM is identical to the stochastic block-

model (Nowicki & Snijders 2001), except that the latter is based on a fixed, *a priori* determined number of groups. IRM shares a lot of common characteristics with other latent variable models (Handcock, AE, & Tantrum 2007; Hoff, Raftery, & Handcock 2002). Formally, this leads to the following decomposition of the likelihood function:

$$p(\boldsymbol{R} \mid identities\ \boldsymbol{I}) = \prod_{i,j} p(R_{i,j} \mid I_i, I_j) \qquad (1)$$

The product above is over all pairs of objects between which links (with value 0 or 1) have been observed. (Note that missing links are omitted.) In a Bayesian setting, the individual likelihoods can be modeled with a Bernoulli distribution with a hyper-parameter $\eta(I_i, I_j)$. Furthermore, a beta distribution $beta(\beta_1, \beta_2)$ can be used as a hyper-prior for each η (Kemp *et al.* 2006). In fact, the η's can be readily integrated out which leads to a simpler expression for the likelihood $p(\boldsymbol{R} \mid identities\ \boldsymbol{I})$ that depends only on the counts $m_0(I, J)$, $m_1(I, J)$ of 0 and 1 links between each pair of identities I, J, respectively:

$$p(\boldsymbol{R} \mid identities\ \boldsymbol{I}) = \prod_{I,J} \frac{beta(m_0(I,J) + \beta_1, m_1(I,J) + \beta_2)}{beta(\beta_1, \beta_2)}$$
$$(2)$$

where $beta(\ ,\ )$ denotes the beta function.

Extensions to real-valued links can be readily obtained by using an appropriate prior for $p(R_{i,j} \mid I_i, I_j)$ (e.g., exponential, gamma, etc). Furthermore, if a vector of attributes $\boldsymbol{x}^{(i)}$ is also observed at each object i, then the likelihood can be augmented as follows:

$$p(\boldsymbol{R}, \boldsymbol{x} \mid identities\ \boldsymbol{I}) = \prod_{i,j} p(R_{i,j} \mid I_i, I_j) \prod_i p(\boldsymbol{x}^{(i)} \mid I_i)$$
$$(3)$$

and an appropriate prior can be defined for the individual likelihoods $p(\boldsymbol{x}^{(i)} \mid I_i)$.

Since the number of identities is unknown *a priori*, a nonparametric prior for I_i's is adopted. This is achieved by a distribution over the space of partitions induced by a Chinese Restaurant Process (CRP) (Antoniak 1974; Ferguson 1973). Of the several mathematical interpretations that have appeared perhaps the simplest is the one in which the CRP arises as the infinite limit of a Dirichlet distribution on the K-dimensional simplex as $K \rightarrow \infty$ (Neal 1991). A fundamental characteristic of the CRP is exchangeability, which simply implies that the probability associated to a certain partition is independent of the order in which objects are assigned to groups. Under the CRP, customers (which in our case correspond to objects) enter a Chinese restaurant sequentially and are assigned to tables (which in our case correspond to groups/identities) according to the following conditional:

$$p(I_N = t \mid \boldsymbol{I_{-N}} = t) = \begin{cases} \frac{n_t}{N-1+a} & \text{if } n_t > 0 \\ \frac{a}{N-1+a} & \text{if } n_t = 0 \end{cases} \qquad (4)$$

where I_N and $\boldsymbol{I_{-N}}$ are the group indicator variables of objects N and $1, 2, \ldots, N-1$, respectively; n_t is the number of objects already assigned to group t. Hence, the Nth object can be assigned to an existing group or to a new group. The number of groups can therefore vary and the parameter a controls the propensity of the model to create new groups. Typically, a gamma prior is adopted, which leads

to a simple expression for the conditional posterior that can then be used in Gibbs sampling (West 1992). Posterior inference with respect to the latent variables I_i can also be performed using Gibbs sampling (Escobar & West 1995; Neal 1998). This simply makes use of the prior conditionals (see Equation (4)) and the likelihood function (see Equation (2)).

IRM is a flexible and lightweight model for group discovery. However, its most significant deficiency is that each object can belong to only a single identity (or group) and all the links that an object participates in arise as a result of that identity. This assumption can be too restrictive, as in general, the identity of each object does not consist of a single component but rather of several components which coexist at different proportions. For example, if the links are friendship and the objects are people, then a person might be friends with other people because they belong to the same social group, or work for the same company, etc. This deficiency is particularly noticeable if several link types are simultaneously considered such as is-friend-of, is-colleague-of, and is-acquaintance-of, where depending on the type, each person exhibits different identities with varying degrees. The next section describes a model that overcomes this deficiency.

Infinite Mixed-Membership Model

Mixed-membership models have been introduced to account for the fact that objects can exhibit several distinct identities in their relational patterns (Airoldi *et al.* 2005; 2006). Posed differently, an object can establish links as a member of multiple groups. This aspect is particularly important in social information processing where social networks can be used for detection of anomalous behaviors/identities. It is unlikely that the objects of interest will exhibit this identity in all their relations. It is of interest therefore to find all the different identities exhibited but also the degree to which these are present in each object's overall identity. These components can be shared among the objects in the same domain but the proportions can vary from one to another.

In order to capture the mixed-membership effect, we alter the aforementioned model by introducing a latent variable for each object and for each observable link that the object participates in. Let $R_{i,j}^m$ be an observable link between objects i and j, where m is an index over all available links. We introduce the latent variables $I_{i,m}$, which denote the identity exhibited by object i in link m. (The index m is redundant with respect to the definition of the link as the participating objects i and j suffice, but it is used herein to facilitate the notation for the latent identity variables.) Similar to IRM (see Equation (1)), we assume that the likelihood can be decomposed as:

$$p(\boldsymbol{R} \mid \boldsymbol{I}) = \prod_m p(R_{i,j}^m \mid I_{i,m}, I_{j,m}) \qquad (5)$$

Hence, (in general) there are several latent variables, say m_i, associated with each object i. Chinese restaurant process priors can be used for each object with a parameter a_i. Although this would produce groupings for each object, these groups will not be shared across objects and therefore would

not be relevant with respect to group discovery in the whole domain. For that purpose, we adopt a hierarchical prior – namely the Chinese Restaurant Franchise (CRF) (Teh *et al.* 2006). Based on the restaurant analog, customers enter several restaurants belonging to a franchise and share the same menu. Their group assignment is based on the dish they end up eating, which is determined in a two-step process. First, the customers in each restaurant are seated based on independent CRPs. Therefore the table assignment $t_{i,m}$ of customer m in restaurant i is defined by:

$$p(t_{i,m} = t \mid \boldsymbol{t_{i,-m}}) = \left\{ \begin{array}{ll} \frac{n_{i,t}}{m_i - 1 + a_i} & \text{if } n_{i,t} > 0 \\ \frac{a_i}{m_i - 1 + a_i} & \text{if } n_{i,t} = 0 \end{array} \right. \qquad (6)$$

where $n_{i,t}$ is the number of customers seated at table t in restaurant i and a_i the parameter of the CRP pertinent to restaurant i. Once the seating has taken place, each table in each restaurant orders sequentially a dish (common for all the occupants of the table) from the common menu. The probabilities are again independent of the order in which this process takes place and are determined by a base CRP with parameter a_0 (denoted by CRP_0):

$$p(d_{i,t} = d \mid \boldsymbol{d_{-(i,t)}}) = \left\{ \begin{array}{ll} \frac{s_d}{M - 1 + a_0} & \text{if } s_d > 0 \\ \frac{a_0}{M - 1 + a_0} & \text{if } s_d = 0 \end{array} \right. \qquad (7)$$

where $d_{i,t}$ is the dish served at table t of restaurant i, s_d is the number of tables (over all restaurants) that have ordered dish d, and M is the total number of tables (over all restaurants). Based on the notation introduced, the group assignment $I_{i,m}$ is equal to $d_{i,t_{i,m}}$ – i.e., the dish served at table $t_{i,m}$ where the customer m of restaurant i was seated. It becomes apparent that the CRPs at the restaurant level express the mixed-membership effect while the base CRP_0 accounts for the groups/identities associated with all the objects. The model is summarized below:

$$\begin{array}{rcl} CRP_0 \mid a_0 & \sim & CRP(a_0) \qquad\qquad (8) \\ I_{i,m} \mid a_i & \sim & CRP(a_i, CRP_0) \\ \eta(I_1, I_2) \mid \beta_1, \beta_2 & \sim & Beta(\beta_1, \beta_2) \\ R_{i,j}^m \mid I_{i,m}, I_{j,m}, \boldsymbol{\eta} & \sim & Bernoulli\left(\eta(I_{i,m}, I_{j,m})\right) \end{array}$$

Equations (6) and (7) readily imply how Gibbs sampling can be performed for posterior inference with respect to the latent variables $I_{i,m}$. The latter is not directly sampled but instead we sample the auxiliary variables $t_{i,m}$ and $d_{i,t}$. For further details, see Teh *et al.* (2006). It should finally be noted that the posterior is a distribution on partitions and therefore exchangeable. If for example we have three objects with a single latent variable for each object and discover two groups, then the group assignment $(1, 2, 1)$ is equivalent (in the sense that the posterior likelihood is the same) to $(2, 1, 2)$. This complicates matters in the sense that posterior inference across several samples cannot be performed with respect to specific groups (as their labels might change from sample to sample). We can however look at the maximum likelihood (or maximum posterior) configuration and calculate degrees of membership as described below.

Quantifying Degree of Membership

Consider a specific configuration drawn from the posterior in which all latent variables $I_{i,m}$ (the customers in our CRF analog) have been associated with tables and dishes (i.e.,

Object Set	Identity 1	Identity 2	Identity 3
Set_1 (Objects 1-10)	1.0	0.0	0.0
Set_2 (Objects 11-20)	0.2	0.8	0.0
Set_3 (Objects 21-30)	0.1	0.1	0.8
Set_4 (Objects 31-40)	0.1	0.4	0.5

Table 1: Degree of membership matrix for synthetic data

identities). We wish to calculate the degree of membership of each object to each of the identities, say K, that have been found. Posed differently, if a new customer $m_i + 1$ arrived at restaurant i what would the probability be that he ends up eating one of the K dishes?

If we consider a dish k, then this probability can be decomposed into the sum of two terms: a) probability that he eats k while seated at one of the existing tables, and b) probability that he eats k while being seated at a new table in restaurant i (which was created to accommodate only him). If T_i is the number of existing tables at restaurant i, then the first term p_a would be:

$$p_a = \sum_{t=1}^{T} p(t_{i,m_{i+1}} = t) \, p(d_{i,t} = k) \qquad (9)$$

The second term in that sum would be either 0 or 1 since all the existing tables have already been assigned one of the K dishes. The first term depends on the $CRP(a_i)$ and can be calculated based on Equation (6).

The probability of the second component p_b (which corresponds to the event that the new customer is being seated at a new table $T_i + 1$ and is served dish k) can be expressed as:

$$p_b = p(t_{i,m_{i+1}} = T_i + 1) \, p(d_{i,T_i+1} = k) \qquad (10)$$

The first term above is given by Equation (6) and the second by Equation (7) as it depends on the number of tables already assigned to dish k.

Experimental Evaluation

This section describes our experiments on a variety of synthetic and real data sets. Degrees of group membership were calculated from the maximum likelihood configuration, which was selected from 10 independent runs with $20K$ MCMC iterations each. A standard version of simulated annealing was used in order to avoid local modes with an initial temperature of 100 and a reduction factor of 0.99. In all experiments, the following hyper-priors were used:

- For β_1, β_2 : independent $Poisson(0.1)$
- For a_0 and a_i's: independent $Gamma(1.0, 1.0)$

Synthetic Data Set

An artificial data set consisting of 40 objects and 3 identities (or groups) was constructed. The objects were divided into 4 sets (Set_1 through Set_4) each consisting of 10 objects. Table 1 lists the degree of membership of each set to the 3 groups.

A matrix containing probabilities of links between any pair of identities was also generated from a $Beta(0.1, 0.1)$ and links were drawn. The full adjacency matrix was then given to the model.

Object Set	Identity 1	Identity 2	Identity 3
Set_1 (Objects 1-10)	0.90	0.06	0.04
Set_2 (Objects 11-20)	0.14	0.82	0.05
Set_3 (Objects 21-30)	0.10	0.12	0.78
Set_4 (Objects 31-40)	0.16	0.30	0.53

Table 2: Degree of membership matrix for IMMM's maximum likelihood configuration on the synthetic data

Table 2 reports the degrees of membership of the 4 sets of objects for the maximum likelihood configuration. IMMM is able to quantify the mixed membership effect with good accuracy. It should also be noted that the maximum likelihood configuration from IRM consists of 7 groups (and not 3 groups), to which the respective objects are assumed to belong exclusively (i.e. 100% membership).

In order to more accurately compare the two models, we calculated the similarity matrix $\boldsymbol{P_0}$ that expresses the probability that any pair of objects belongs to the same group. For example, (based on Table 1) the probability that an object from Set_2 is in the same group with an object from Set_3 is $(0.2 \times 0.1) + (0.8 \times 0.1) + (0.0 \times 0.8) = 0.1$. This was compared with the similarity matrices calculated by IRM ($\boldsymbol{P_{IRM}}$) and IMMM ($\boldsymbol{P_{IMMM}}$) by averaging over the posterior samples. Figure 1 depicts the absolute values of the deviations – i.e., $\mid P_{IRM}^{i,j} - P_0^{i,j} \mid$ and $\mid P_{mm}^{i,j} - P_0^{i,j} \mid$, $\forall i,j$ object-pairs. The errors are much smaller for IMMM, particularly within Set_3 and Set_4, which exhibit the most significant mixed-membership characteristics. In fact, the ratio of the *Frobenius error norm* is $\frac{||\boldsymbol{P_{IMMM}} - \boldsymbol{P_0}||}{||\boldsymbol{P_{IRM}} - \boldsymbol{P_0}||} \approx 0.19$.

Another comparison metric is the *full-sample log-score* (LS_{FS}), which is defined as the average over all observable links $\boldsymbol{R_{i,j}}$ (Chen, Shao, & Ibrahim 2000; Krnjajic, Kottas, & Draper 2006). This metric is especially useful in real-world data sets where the ground-truth is unknown. It is formally defined as:

$$LS_{FS} = \frac{1}{M} \sum_{R_{i,j}} \log p(R_{i,j} \mid \boldsymbol{R}, \boldsymbol{I}, \boldsymbol{\theta}) \qquad (11)$$

where $\boldsymbol{I}$ represents the latent variables indicating the identities and $\boldsymbol{\theta}$ the hyper-parameters (e.g., $\boldsymbol{\theta} = (\beta_1, \beta_2, a)$ for IRM). $p(. \mid .)$ expresses the posterior predictive distribution, which can be readily calculated by averaging over the posterior samples. It should be emphasized that the observables $\boldsymbol{R}$ are not used twice but rather we choose to evaluate the posterior predictive distribution at those points.

LS_{FS} can be calculated using one MCMC run. This is in contrast to the *cross-validation log-score* LS_{CV} (a.k.a. *perplexity*) (Chen, Shao, & Ibrahim 2000), which requires $O(M)$ independent MCMC runs (where M is the total number of observable links). Besides for large M, leaving a small set of observable out does not in general have a significant effect. Lastly, LS_{FS} has favorable properties over Bayes factors and is applicable to nonparametric models (Krnjajic, Kottas, & Draper 2006).

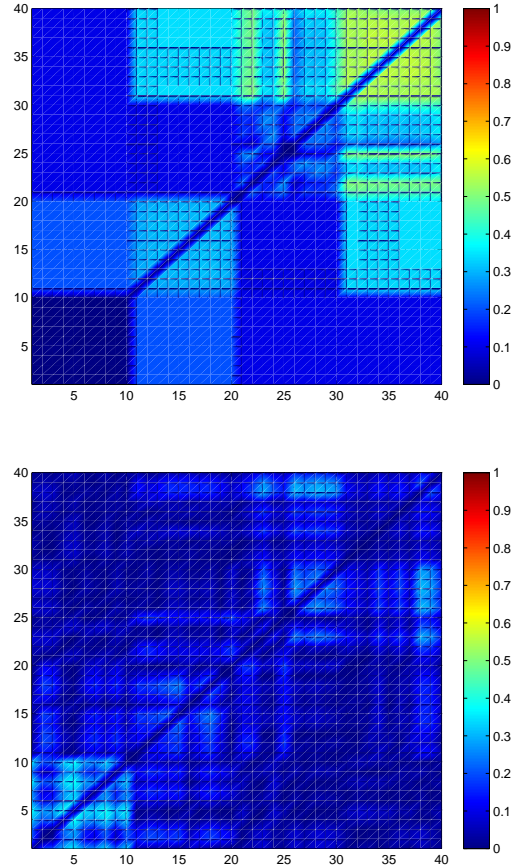For our synthetic data, the LS_{FS} values for IRM and IMMM were -0.53 and -0.51, respectively. A higher LS_{FS}

Figure 1: $\mid P_{IRM}^{i,j} - P_0^{i,j} \mid$ (top) and $\mid P_{IMMM}^{i,j} - P_0^{i,j} \mid$ (bottom) for all pairs of objects i, j. $P_M^{i,j}$ is the average over posterior samples that model M gives to i, j belonging to the same group. $M = 0$ represents the true model. The deviation matrix with entries closer to zero (i.e., the bottom one) is modeling the data better.

score denotes a more accurate model.

Real Data Sets

We tested our model on three real social networks (namely, Zachary's Karate Club, U.S. Political Books, and MIT Reality Mining) and one bipartite graph (namely, the Animal-Feature data). The latter shows how our model can be extended to data sets with more than one domain. A description of each data set follows next.

The Animal-Feature data set consists of two domains – i.e., objects of two different types. In particular, the first domain consists of 16 animals and the second of 13 features (source: http://www.ifs.tuwien.ac.at/∼andi/somlib/). Binary links indicate whether the animal has the particular feature. The animal domain consists of two basic groups: birds and 4-legged mammals. Some of the features are shared between the two basic groups. For example, even though the eagle is a bird, it has certain features in common

with the mammals such as its medium size, being a hunter, and not being able to swim. Similarly, even though the cat is a 4-legged mammal, it shares some features of small-sized birds that cannot run.

Zachary's karate club (Zachary 1977) is a well-studied social network. It consists of 34 individuals which initially belonged to the same club but due to a disagreement between the administrator and the instructor ended up splitting into two. Figure 2 illustrates the network's topology (Girvan & Newman 2002). Members that aligned with the instructor (object 1) are marked with squares (group 1) and members that favored the administrator (object 34) are marked with circles (group 2). It is interesting to note that even though two individuals can belong to the same group (e.g., individuals 3 and 13 both are in group 1), their group affiliations are vastly different (e.g., individual 3 is closer to group 2 than individual 13). For this data, we used a binary version of the friendship links as observables.
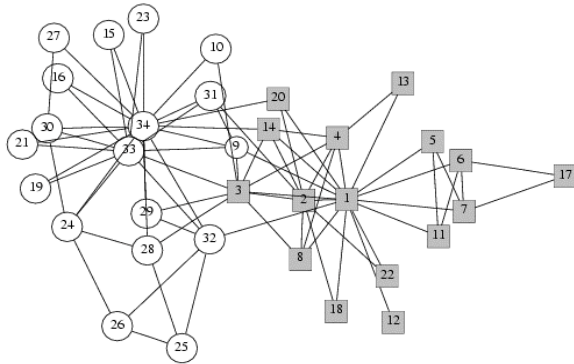

Figure 2: Friendship network for Zachary's karate club (Girvan & Newman 2002)

The U.S. Political data set consists of 105 political books sold by an online bookseller in 2004. The data was assembled by V. Krebs (source: http://www.orgnet.com/). Links were created based on frequent co-purchasing of books by the same buyers. The books have been assigned three labels (liberal, conservative and neutral) by M.E.J. Newman (http://www-personal.umich.edu/~mejn/) based on reviews and descriptions of the books.

The MIT Reality Mining data set utilizes proximity data for 97 individuals collected over a single week during the academic year 2004-2005 (source: http://reality.media.mit.edu/). Each person was given a cell phone with a blue-tooth device that registered other bluetooth devices that were in close physical proximity. The individuals participating in this experiment were (*i*) Sloan Business School students, (*ii*) faculty, staff and students of the MIT Media Lab and (*iii*) others. In the latter category, a single object represents all outsiders.

Table 3 depicts the LS_{FS} scores for IRM and IMMM on four real data sets. IMMM's LS_{FS} scores are greater than IRM's in all four cases. (Again higher LS_{FS} scores indicate a better model.)

Data set	IRM	IMMM
Animal-Feature	-0.30	-0.29
Zachary's Karate Club	-0.15	-0.13
U.S. Political Books	-0.15	-0.09
Reality Mining	-0.27	-0.23

Table 3: Full-sample log-score LS_{FS} on real data sets

Discussion For the Animal-Feature data, Figure 3 depicts the comparison of two rows of the similarity matrix as calculated by IRM and IMMM. In particular, we calculated the posterior probabilities that the eagle and the cat belong to the same group with any other animal in the domain. Since this is an unsupervised learning task, values for these probabilities are important in a relative sense rather than an absolute sense. As it can be seen, IRM assigns high values that the eagle belongs to the same group with the other birds but practically zero for the mammals. This is a direct consequence of IRM's inability to capture the possibility that the eagle might simultaneously belong to another group. The results are significantly better with IMMM which predicts higher probabilities that the eagle is in the same group with the rest of the birds, but also has considerable similarities with the mammals reflecting the fact that some of their features are shared. For example, the eagle is of medium-size like fox, dog, and wolf; it also hunts like some of the cat-family members. Similar results are observed in the case of the cat where IMMM is shown to have superior performance.
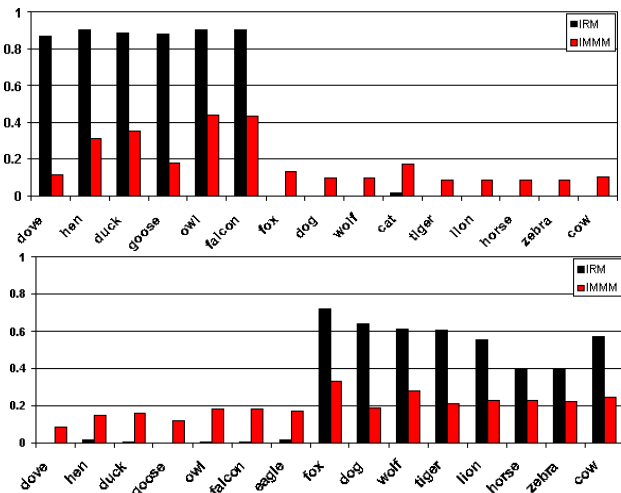

Figure 3: Posterior probabilities that the eagle (top) and the cat (bottom) belong to the same group with any of the other animals in the data set.

For Zachary's Karate Club data, IMMM's maximum likelihood configuration identified 4 identities/groups. IRM's maximum likelihood configuration identified 7 groups. Figure 4 depicts the degrees of membership for each object. One can observe that identity 1 corresponds to the hard core of group 1, which consists primarily of the instructor (indi-

vidual 1) and to a lesser extent by 2, 4, 5, 6, and 11. Identity 2 represents the "outer layer" (or soft core) of group 1 (i.e. the remaining members of group 1). Similarly, identity 3 denotes the outer layer of group 2. Finally, identity 4 consists of the administrator (individual 34) and a few other closely related individuals such as 33, 24, 25, 26, etc. It is important to note that our model is able to quantify mixed-membership effects. For example, individual 3 belongs to group 1 but also has a considerable number of links with the hard (individual 33) and soft (individuals 10 and 29) cores of group 2; so it exhibits all 4 identities (though primarily those of group 1). Similarly individuals 9, 10, 31, and 32 (which belong to group 2) exhibit in their identities a component of group 1 due to their relations with other people from that group.
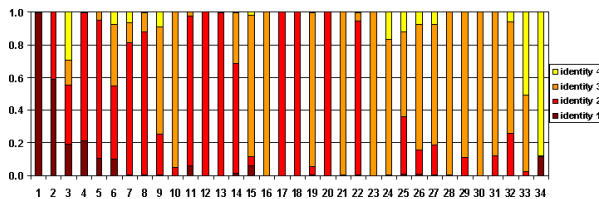

Figure 4: IMMM identities on the Zachary's Karate Club Friendship network. These identities are associated with the maximum likelihood configuration.

Conclusions

Bayesian latent variable models provide a valuable tool for social network analysis in such tasks as group discovery and link prediction. Their descriptive ability is significantly increased by using nonparametric priors, which allow for the number of groups to be learned automatically from the data. IRM is hampered by the assumption that each object belongs to a single group. In this paper, we introduced a mixed-membership model that allows each object to belong simultaneously to several groups. Our model is based on a hierarchical version of the CRP (namely, the Chinese Restaurant Franchise) and inference is readily performed using Gibbs sampling. The proposed model combines all the advantages of IRM and has superior performance in several synthetic and real-world data sets. In particular, our model is expressive enough that it can handle an important problem in social information processing, where one account (say on Amazon.com) is used by several people (like a family) with different interests and hobbies. Future work include extensions for hierarchical group structures and inclusion of time.

Acknowledgments

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